Stochastic modelling in Mathematical Biology

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March 4th 2013



Seminari Informal de Matemàtiques de Barcelona

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Outline

Introduction

Master Equation and Monte Carlo methods

Kinetic Chemical Reactions and the Gillespie Stochastic Simulation Algorithm

Examples

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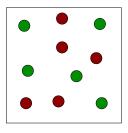
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Motivation

- There exists the general idea that randomness and noise simply add an unsystematic perturbation to a well-defined average behaviour.
- I will present several examples of systems in which noise contributes to the behaviour of the system in a non-trivial manner and it is fundamental to understanding the system.
- From these examples I will extract rules of thumb for ascertaining when randomness plays a fundamental roles.
- I will show you how to modelize some natural process in a better way than using a continuous and deterministic approach.

The Moran Process

The Moran process, named after the australian statistician Pat Moran, is a widely-used variant of the Wright-Fisher model and is commonly used in population genetics.



- N individuals of two types. N is keep fixed.
- n: number of normal individuals. m: number of mutant individuals. N=m+n.
- At each time step:
 - $n \to n+1$ and $m \to m-1$ with probability rate $W_+(n) = \frac{n}{N} \left(1 \frac{n}{N}\right)$.
 - $n \to n-1$ and $m \to m+1$ with probability rate $W_{-}(n) = \frac{n}{N} \left(1 \frac{n}{N}\right)$.

The Moran Process

- Note that W(n+1) = W(n-1), i.e. $\mathbb{E}[\Delta n] = \mathbb{E}[n(t+\Delta t) n(t)] = 0$.
- This implies that with $m = \mathbb{E}[n]$:

$$\frac{dm}{dt} = 0 \tag{1}$$

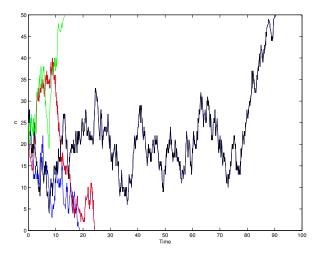
- The system has two absorving states: $W_+(n=0) = W_-(n=0) = 0$ and $W_+(n=N) = W_-(n=N) = 0$
- This means that

$$\lim_{t \to \infty} P(n(t) = 0 \quad \cup \quad n(t) = N) = 1$$
(2)

• This behaviour is not at all captured by the deterministic equation, which predicts that the population will stay constant.

The Moran Process

Simulation results:



Logistic growth

• The logistic equation,

$$\frac{dm}{dt} = m\left(1 - \frac{m}{K}\right),\tag{3}$$

has two steady states: m = 0 unstable and m = K stable, i.e. regardless of the value of K and for any initial condition such that m(t = 0) > 0, m(t) will asymptotically approach K.

- Consider now a continuous-time Markov process *n_t* whose dynamics are given by the following transition rate:
 - $n \rightarrow n+1$ with probability rate n.
 - $n \to n-1$ with probability rate $\frac{n(n-1)}{2} \frac{1}{K}$.
- This stochastic process has a unique absorbing state: n = 0, and therefore we expect the stochastic dynamics to show strong discrepancies with Equation (3) when randomness is dominant.

Logistic growth

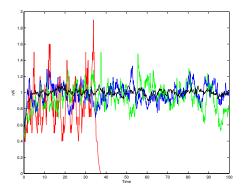


Figure: Red line K = 10, green K = 50, blue K = 100, black K = 1000

We observe that for small K fluctuations dominate the behaviour of the system. Extinctions are common for small K , in contradiction to the behaviour predicted by the logistic equation Eq. (3), and become rarer as K is allowed to increase.

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Steady states vs Absorbing states

- The definition of equilibrium states in stochastic systems is a bit technical and there are several definitions of equilibrium.
- Consider again the stochastic logistic growth, i.e. a process n_t such that:
 - $n \rightarrow n+1$ with probability rate $W_+(n) = n$
 - $n \to n-1$ with probability rate $W_{-}(n) = \frac{n(n-1)}{2} \frac{1}{K}$
- Consider a state of system, n_s , is, roughly speaking, a state of the process such that $W_+(n_s) = W_-(n_s)$.
 - $W_+(n_s)$ is the number of births within a population of n_s individuals
 - Likewise, $W_{-}(n_{s}) =$ the number of deaths within a population n_{s} individuals
 - So an steady state of our population dynamics is reached when $n_t = n_s$, since death rate is balanced by birth rate and therefore the population stays roughly constant
- $n_s = K$ which coincides with the deterministic stable fixed point.
- Note that $W_+(n) W_-(n) > 0$ if $n < n_s$ and $W_+(n) W_-(n) < 0$ if $n > n_s$

Steady stats vs Absorbing states

- An absorbing state, n_0 , is characterised by $W_i(n_0) = 0$ i.e. once the system has reached the absorbing state, it cannot leave anymore.
- Consider again, the stochastic logistic growth rate, we have:
 - Steady states are in general not absorbing states.
 - $W_+(n_s) \neq 0$ and $W_+(n_s) \neq 0$.
 - If n = 0 then $W_+(0) = W_-(0) = 0$ therefore n = 0 is an absorbing state.
- n_s belongs to the set of accessible states of n = 0, that means there is at least one consecutive set of transition that connects n_s and n₀. For Example:
 K → K − 1 → K − 2 → ··· → 1 → 0.
- $\bullet\,$ However, if ${\cal K}\gg 1$ the probability of such a chain of events is vanishingly small.

Summary

- n_s is an steady state in the sense that births and deaths are balanced. Moreover, $W_+(n) - W_-(n) > 0$ if $n < n_s$ and $W_+(n) - W_-(n) < 0$ if $n > n_s$. This is essentially equivalent to what happens in the deterministic logistic growth model.
- However, n_s is not an absorbing state of the stochastic dynamics. The only absorbing state is n = 0.
- Stochastic extinctions are relatively rare provided *K* is big. If this is the case, the deterministic system provides a reasonable approximation to the behaviour of the model.
- If, on the contrary, K is small stochastic extinctions are relatively common and the deterministic description is not an accurate one
- We have seen several examples of stochastic systems in which noise and randomness are the dominating factors. Their behaviours are not captured by their deterministic conterparts.
- In general, we should expect non-trivial random effects for small populations or dynamics with absorbing states.

Outline

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The Master Equation

- The Master Equation is our fundamental mathematical description of an stochastic process and the starting point for any attempt to analyse a particular model.
- It is obtained as a probability balance for all the events that can occur during the time intertal $(t, t + \Delta t)$.
- Mathematically, it is a set of ordinary differential equations for the probability distribution P(n, t) i.e. the probability that the number of individuals in the population at time t to be n.

The Master Equation II

Example: Birth and death process

- Birth n → n + 1 with probability rate W₊(n) = λn. Death: n → n − 1 with probability rate W₋(n) = σn.
- Probability balance:
 - $P(n, t + \Delta t) = \lambda(n-1)\Delta tP(n-1, t) + \sigma(n+1)\Delta tP(n+1, t) + (1 (\lambda n\Delta t + \sigma n\Delta t))P(n, t).$

• When
$$\Delta t \rightarrow 0$$
:

$$\frac{dP(n,t)}{dt} = \lambda(n-1)P(n-1,t) + \sigma(n+1)P(n+1,t) - (\lambda n + \sigma n)P(n,t)$$

• **Big Problem:** In general is not possible to get the analytical solution of the Master Equation, even a numerical solution of the Master Equation can be very hard.

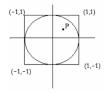
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Monte Carlo Simulations

- The first thoughts and attempts made to practice the Monte Carlo Method were suggested by a question which occurred in 1946 to Stanislaw Ulam was convalescing from an illness and playing solitaires. The question was what are the chances that a Canfield solitaire laid out with 52 cards will come out successfully?
- After spending a lot of time trying to estimate them by pure combinatorial calculations, he wondered whether a more practical method than "abstract thinking" might not be to lay it out say one hundred times and simply observe and count the number of successful plays.
- In 1950s Stanislaw Ulam and John von Neumann started a research in this topic founded by The RAND Corporation and the U.S. Air Force.
- Uses of Monte Carlo methods require large amounts of random numbers, and it was their use that spurred the development of pseudorandom number generators.

Monte Carlo Simulations

- There is no consensus on how Monte Carlo method should be defined.
- Example: Approximate the value of π
 - Consider a random point P in the unit square, which is the probability that P is in the unit circle?



- The probability has to be the quotinet of the areas, that is $\frac{\pi}{4}$.
 - a Set Ok = 0
 - b Generate two random numbers $x, y \in [-1, 1]$ if $x^2 + y^2 < 1$, then Ok = Ok + 1 c Repeat it N times. When $N \to \infty$, then $\frac{Ok}{N} \to \frac{\pi}{4}$

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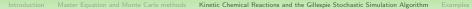
Kinetic Chemical Reactions and the Gillespie Stochastic Simulation Algorithm

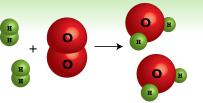
Examples

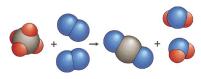
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A Chemical Reacting System

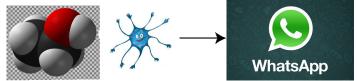
- Molecules of N chemical species $S_1, ..., S_N$
 - Inside some volume $\Omega,$ at some temperature ${\mathcal T}.$
- Interacting through M elemental reaction channels $R_1, ..., R_M$.
- *R_j* is assumed to describe a single instantaneous physical event which changes the population of at least one species.







 $CH_4 + 2O_2 \longrightarrow CO_2 + 2H_2O$



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Deterministic vs Stochastic

The time-evolution of chemical systems has traditionally been analyzed using continuous, deterministic mathematics (ODEs, PDEs).

But in fact, chemical systems evolve

- Discretely, because molecules come in integer numbers
- Stochastically, for several reasons:
 - Even if all the molecules moved according to deterministic Newtonian mechanics, the system is so sensitive to initial conditions that is behaviour will be random.
 - Chemical systems of practical interest are NEVER isolated. The reason why a system is a temperature T is because it is having random exchanges of energy with its environment.
 - All unimolecular reactions $S \rightarrow$ anything are inherently stochastic.

Deterministic vs Stochastic

For the simplest chemical reaction: $S
ightarrow \emptyset$

• Traditional wisdom asserts that $X(t) \equiv$ the number of S molecules in the system at time t, evolves according to the ODE

$$\frac{dX(t)}{dt} = -cX(t). \tag{4}$$

- But **physics** \implies the S molecules react independently of each other.
- The problem: There is no plausible physical mechanism that could give rise to such exquisitely coordinated deterministic behavior!
- The most reasonable mechanism for $S \to \emptyset$ is that the lifetimes of the individual S molecules are i.i.d. random variables. In that case (4) might describe how the average S population evolves in time:

$$\frac{dX_{avg}(t)}{dt} = -cX_{avg}(t).$$
(5)

• If the average S population evolves according to (5), then the lifetime of each S molecule must be an exponential random variable with mean $\frac{1}{c}$, or equivalently,

 $c \cdot dt = \text{Prob}\{\text{a given } S - \text{molecule will die in the next } dt\}$

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Proof of this result:

• With x₀ molecules at time 0, the ODE (5) implies

$$X_{avg}(t) = x_0 e^{-ct} \quad (t > 0)$$

- Let f(τ) denote the cdf of the molecule lifetime. Then for any t > 0, (1 − f(t)) = the probability that any particular one of the x₀ molecules at time 0 will stil be alive at time t.
- So the probability that exactly x moelcules will be alive at this t time is:

$$(1-f(t))^{x}(f(t))^{x_{0}-x}\frac{x_{0}!}{x!(x_{0}-x)!}$$

- From these expressions we obtain $f(t) = 1 e^{-ct}$. This is the cdf of the exponential random variable with mean $\frac{1}{c}$.
- The corresponding pdf $p(t) \equiv df(t)/dt = ce^{-ct}$ is such that $p(t)dt = \text{Prob}\{$ the molecule will die in $[t, t + dt)\}$. Thus, p(0)dt = c dt. **QED**

This has some implications:

- The deterministic equation $\frac{dX}{dt} = -cX$ for $S \to \emptyset$ makes no sense physically unless there is an underlying stochastic dynamics for the *S* molecules.
- And not just any stochastic dynamics, but a stochastic dynamics of a very particular kind: Each *S* molecules must disappear in the next *dt* with probability *c* · *dt*.
- If the S molecules don't behave in that way, then the equation $\frac{dX}{dt} = -cX$ will not correctly describe the reaction $S \to \emptyset$.
- No fundamental physical theory of chemical kinetics can be premised on a traditional ODE like $\frac{dX}{dt} = -cX$. Such an ODE can be, at best, a consequence of a more fundamental theory, and perhaps only an approximate consequence.

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A tractable discrete-stochastic mathematical description of chemically reacting systems is possible if successive reactive collisions between molecules tend to be separated in time by very many non-reactive collisions.

- In that case, the many non-reactive collisions tend to randomize
 - the velocities of the molecules (Maxwell-Boltzmann distribution),
 - the positions of the molecules (randomly uniform inside $\boldsymbol{\Omega}$).
- Then, instead of having to describe the systems state by giving the position, velocity and species of every molecule in Ω , we can get away with specifying the much lower dimensional vector function.

$$X(t) = (X_1(t), ..., X_N(t)),$$

provided its ith component, $X_i(t)$ the number of S_i molecules in Ω at time t, is treated as a random variable. Each raction channel R_j can then be characterized by **two entities**:

• Its **propensity function** $a_j(x)$: If the system is currently in state x,

 $a_j(x) \cdot dt :=$ probability that one R_j event will occur in the next dt.

The existence and form of $a_j(x)$ must come from molecular physics.

• Its state change vector $v_j \equiv (v_{1j}, ..., v_{Nj})$:

 $v_{i,i}$ = the change in X_i caused by one R_i event.

 R_j induces the state change $x \rightarrow x + v_j$.

- Examples:
 - $S_1 \rightarrow S_2$: $v_j = (-1, 1, 0, ..., 0)$; $a_j(x)dt = (c_jdt)x_1 \implies a_j(x) = c_jx_1$
 - $S_1 + S_2 \rightarrow 2S_2$: same v_j ; $a_j(x)dt = (c_jdt)x_1x_2 \implies a_j(x) = c_jx_1x_2$

The Gillespie stochastic simulation algorithm (SSA)

A procedure for constructing sample paths or realizations of X(t):

- Idea: Generate properly distributed random numbers for
 - the time τ to the next reaction
 - the index *j* of that reaction
- $p(\tau, j|x, t) \cdot d\tau \equiv$ probability, given X(t) = x, that the next reaction will occur in $[t + \tau, t + \tau + d\tau)$, and will be R_i .



$$\sum_{k=1}^{M} a_k(x) \equiv a_0(x)$$
$$p(\tau, j|x, t)d\tau = \left(1 - a_0(x)\frac{\tau}{n}\right)^n a_j(x)d\tau \to e^{-a_0(x)\tau}a_j(x)d\tau$$

• Therefore, $p(\tau, j|x, t)d\tau = e^{-a_0(x)\tau}a_j(x)d\tau = a_0(x)e^{-a_0(x)\tau} \cdot \frac{a_j(x)}{a_0(x)}d\tau$

- τ is the exponenital r.v. with mean $\frac{1}{a_0(x)}$.
- j is the integer r.v. with probability mass $\frac{a_j(x)}{a_0(x)}$.
- τ and *i* are statistically independent.

The Gillespie stochastic simulation algorithm (SSA)

The following scheme is a Method of implementing the SSA

- 1 In state x at time t, evaluate $a_1(x), ..., a_M(x)$ and $a_0(x) = \sum_{k=1}^M a_k(x)$.
- 2 generate r_1 and r_2 random numbers in [0, 1], and compute τ and j according to

•
$$\tau = \frac{1}{a_0(x)} ln\left(\frac{1}{1-r_1}\right)$$
,
• $j =$ the smallest integer satisfying $\sum_{k=1}^{j} a_k(x) > r_2 a_0(x)$.

- 3 $t = t + \tau$ and $x = x + v_j$
- 4 Record (x, t). Go to 1 or end the simulation.

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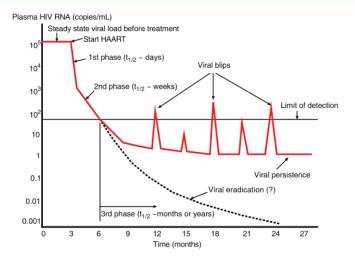
This kind of models can be used in a lot of situations:

- Chemistry, modelling chemical reactions.
- Ecology, for instance in prey predator systems:
 - Wolfs and rabbits.
 - Bougainvillea (Brazilian plant) and Lepidoptera (bug).
- Biological and medical problems:
 - Mutant invasions.
 - Populations of cells and virus.

HIV-1

- An HIV-1 infected person without any treatment has between 10^5 and 10^6 copies of virus per milliliter of blood.
- Following initiation of highly active antiretroviral therapy (HAART) the plasma viral load declines fast. After several months of treatment, most patients attain a level of plasma HIV-1 RNA below the detection limit (50 copies/mL).
- This does not imply that viral replication has been completely suppressed by therapy.
- Even in patients with "undetectable" plasma viral loads for many years, a low level of virus can be detected in plasma by supersensitive assays.
- An explanation is that HIV-1 establishes a state of latent infection in resting memory CD4⁺ T cells, and virus is released when these cells encounter their relevant antigens and are activated.
- Observation of transient episodes of viremia ("blips") above the detection limit.

Summary



Rong L, Perelson AS (2009) Modeling HIV persistence, the latent reservoir, and Viral Blips in HIV-infected Patients on Potent Therapy. J Theor Biol 260: 308-31

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Experimental results

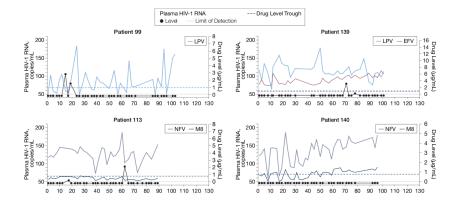
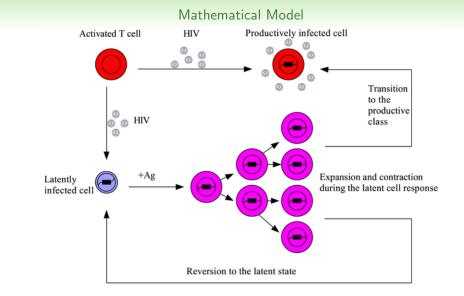


Figure: Experimental results from Nettles et. al

Nettles TE, Kieffer TL, Kwon P, Monie D, Han Y, et al. (2005) Intermittent HIV-1 viremia (Blips) and drug resistance in patients receiving HAART. JAMA 293: 817-829.



Rong L, Perelson AS (2009) Modeling HIV persistence, the latent reservoir, and Viral Blips in HIV-infected Patients on Potent Therapy. J Theor Biol 260: 308-31

Simulations

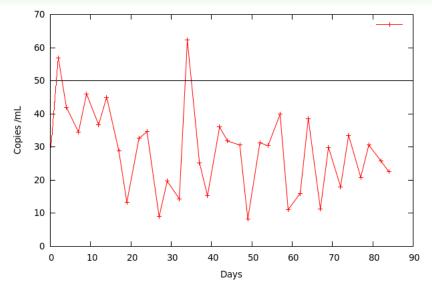


Figure: Gillespie Simulations of our system.

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Simulations

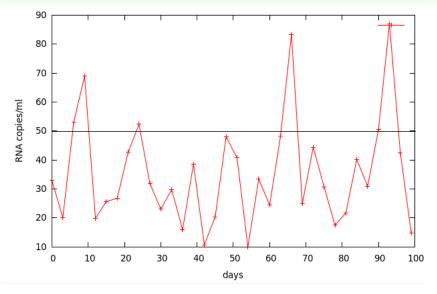


Figure: Gillespie Simulations of our system.

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THANK YOU

FOR YOUR ATTENTION !!

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